

# **Symstra: A Framework for Generating Object-Oriented Unit Tests using Symbolic Execution**

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# Motivations

- Object-oriented unit tests consist of sequences of method invocations.
- Behavior of an invocation depends on the method's arguments and the state of the receiver at the beginning of the invocation.
- Automated test-input generation needs to produce:
  - Method sequences building relevant receiver object states
  - Relevant method arguments

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**Symstra** achieves both tasks using symbolic execution of method sequences with symbolic arguments

# Outline

- Motivations
- Example
- Test generation by exploring concrete states
- Symstra: exploring symbolic states
- Evaluation
- Conclusion

# Binary Search Tree Example

```
public class BST implements Set {  
    Node root;  
    int size;  
    static class Node {  
        int value;  
        Node left;  
        Node right;  
    }  
    public void insert (int value) { ... }  
    public void remove (int value) { ... }  
    public boolean contains (int value) { ... }  
    public int size () { ... }  
}
```

# Previous Test-Generation Approaches

- Straightforward approach: generate all (bounded) possible sequences of calls to the methods under test
  - too many and many are redundant [Xie et al. 04]

Test 1:

```
BST t1 = new BST();  
t1.size();
```

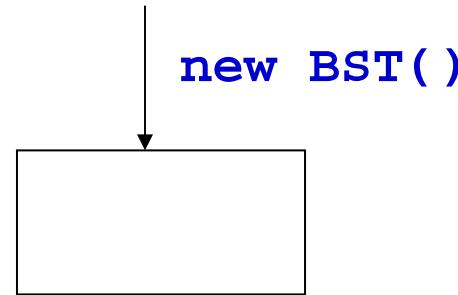
Test 2:

```
BST t2 = new BST();  
t2.size();  
t2.size();
```

- Concrete-state exploration approach  
[Willem et al. 04, Xie et al. 04]
  - assume a given set of method call arguments
  - explore new receiver-object states with method calls (in breadth-first manner)

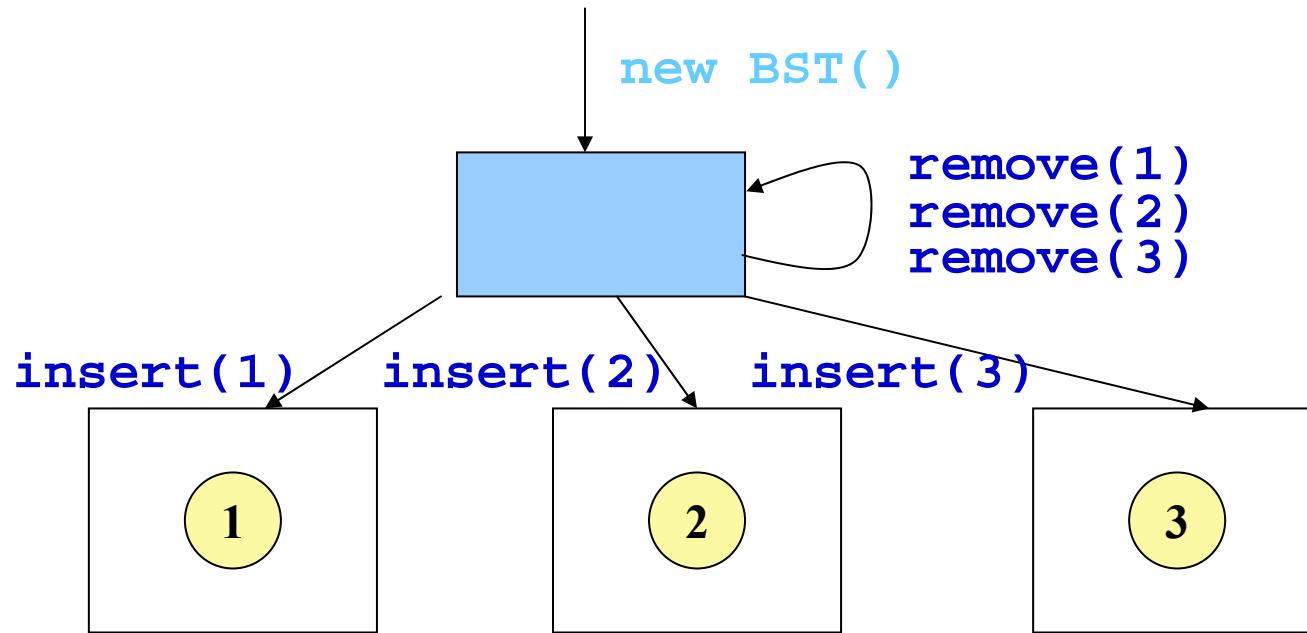
# Exploring Concrete States

- Method arguments: `insert(1)`, `insert(2)`,  
`insert(3)`, `remove(1)`, `remove(2)`, `remove(3)`



# Exploring Concrete States

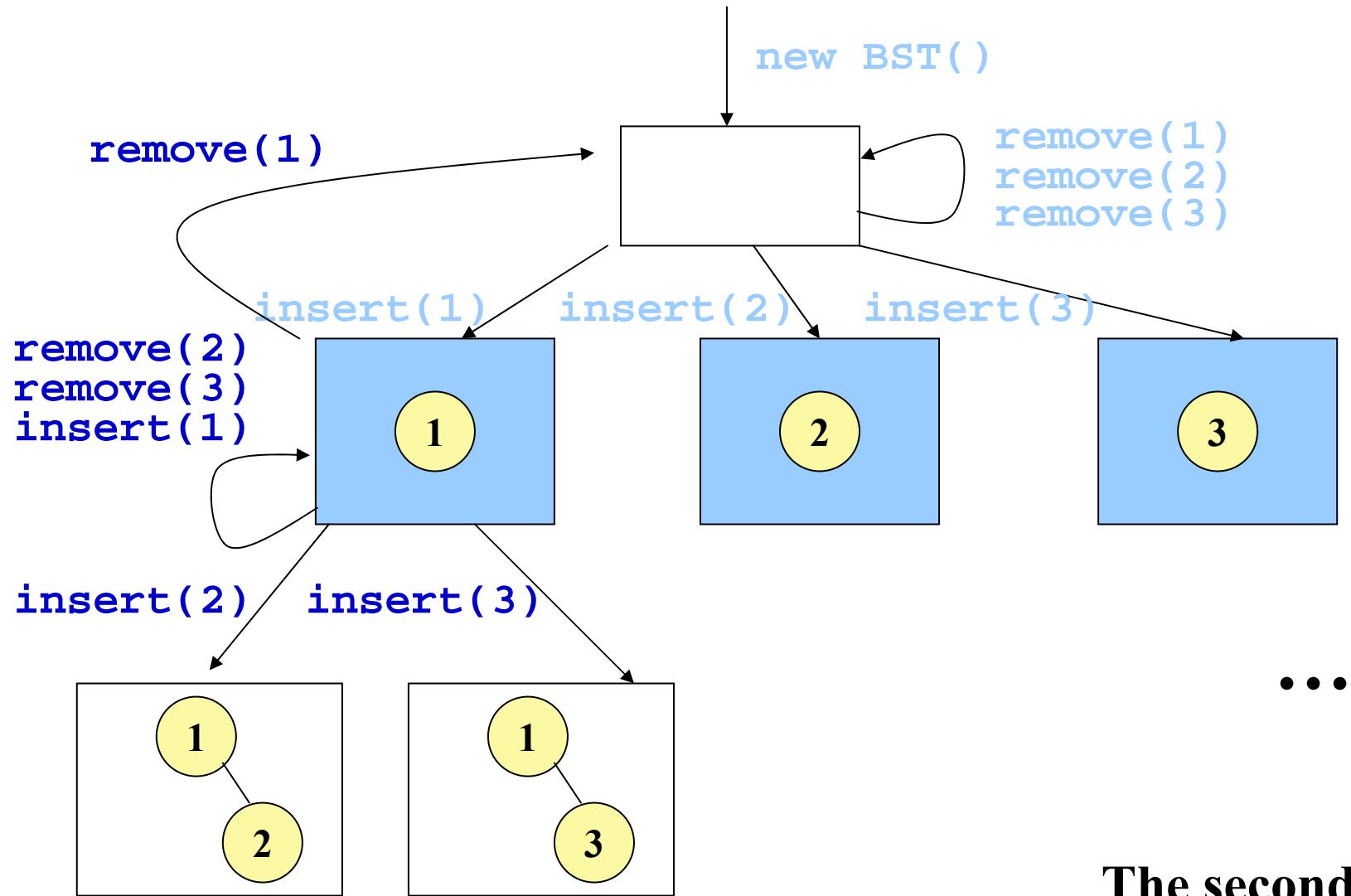
- Method arguments: `insert(1)`, `insert(2)`, `insert(3)`, `remove(1)`, `remove(2)`, `remove(3)`



The first iteration

# Exploring Concrete States

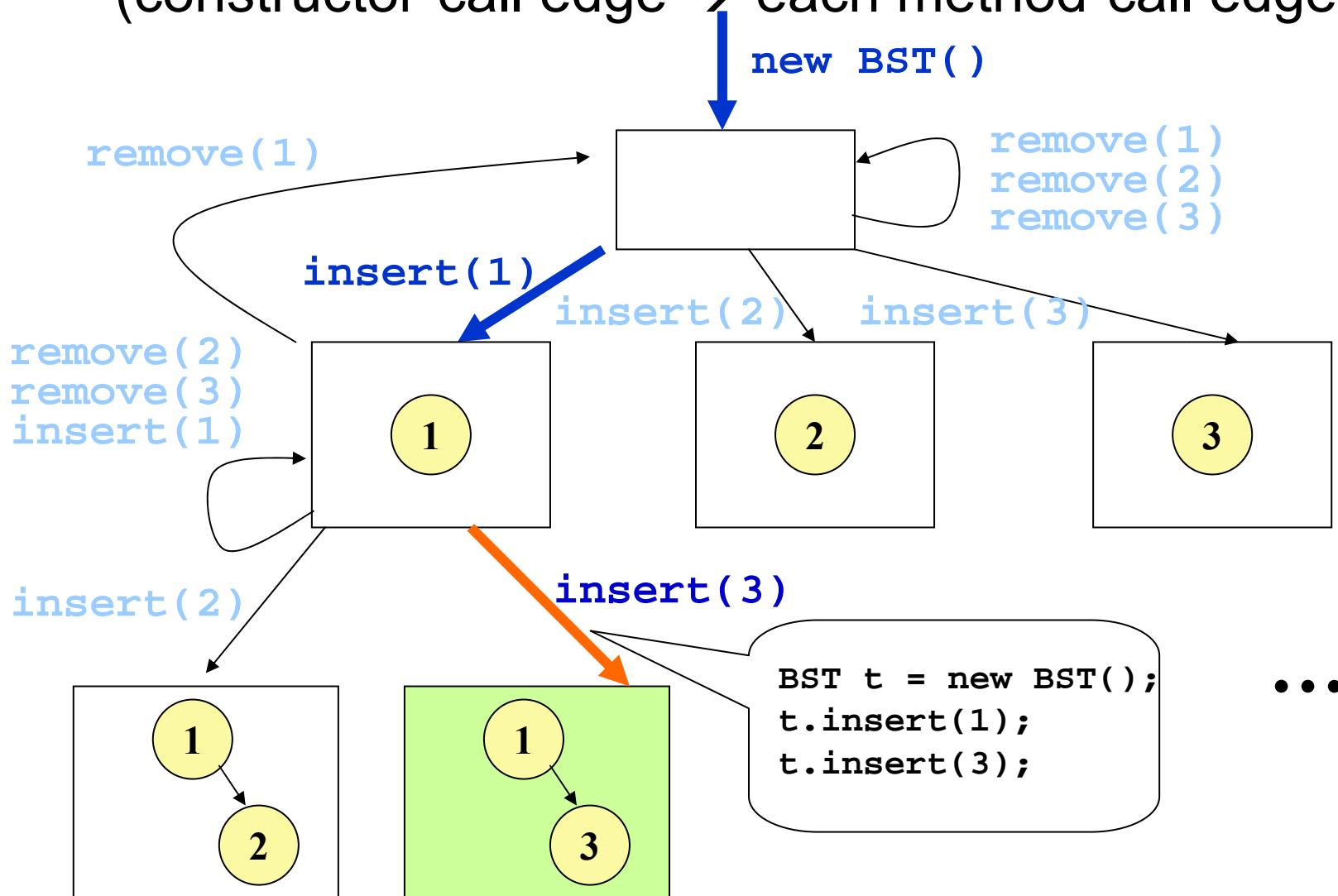
- Method arguments: `insert(1)`, `insert(2)`, `insert(3)`, `remove(1)`, `remove(2)`, `remove(3)`



The second iteration

# Generating Tests from Exploration

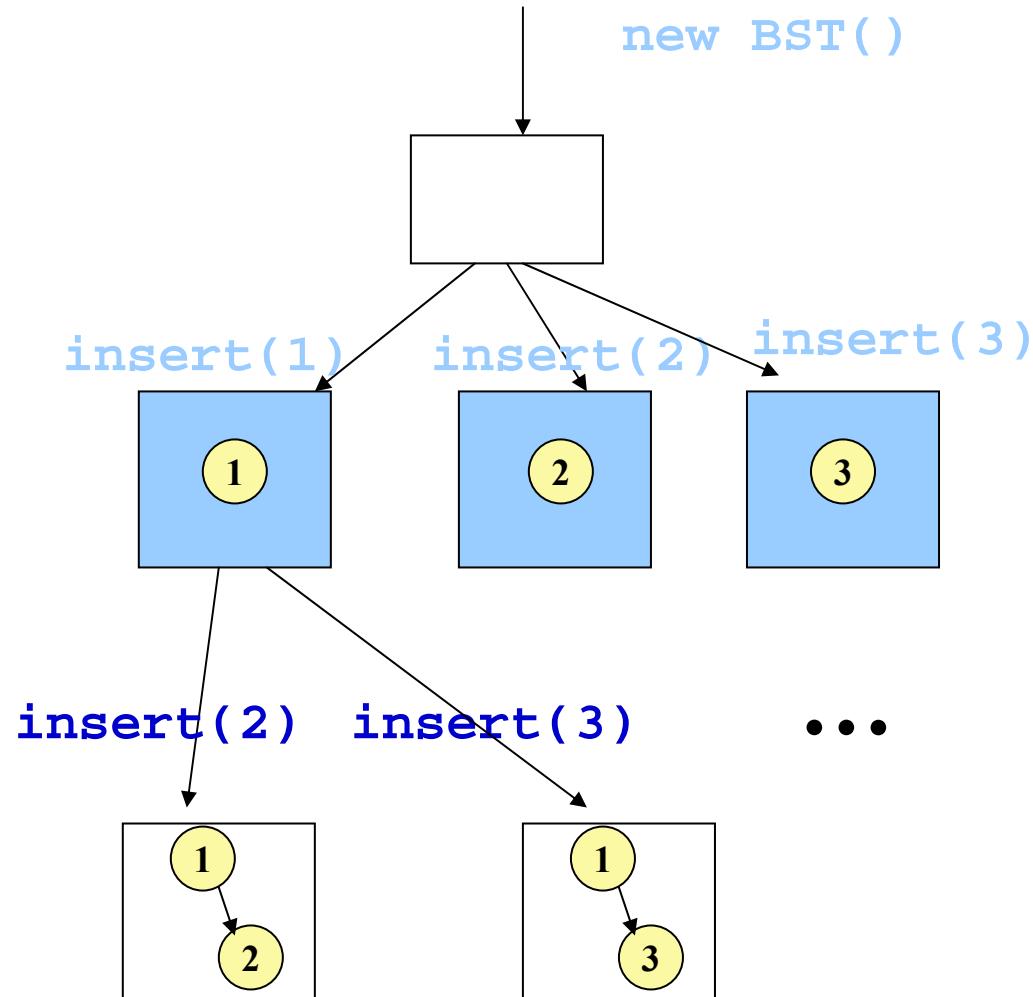
- Collect method sequence along the shortest path  
(constructor-call edge → each method-call edge)



# Issues of Concrete-State Exploration

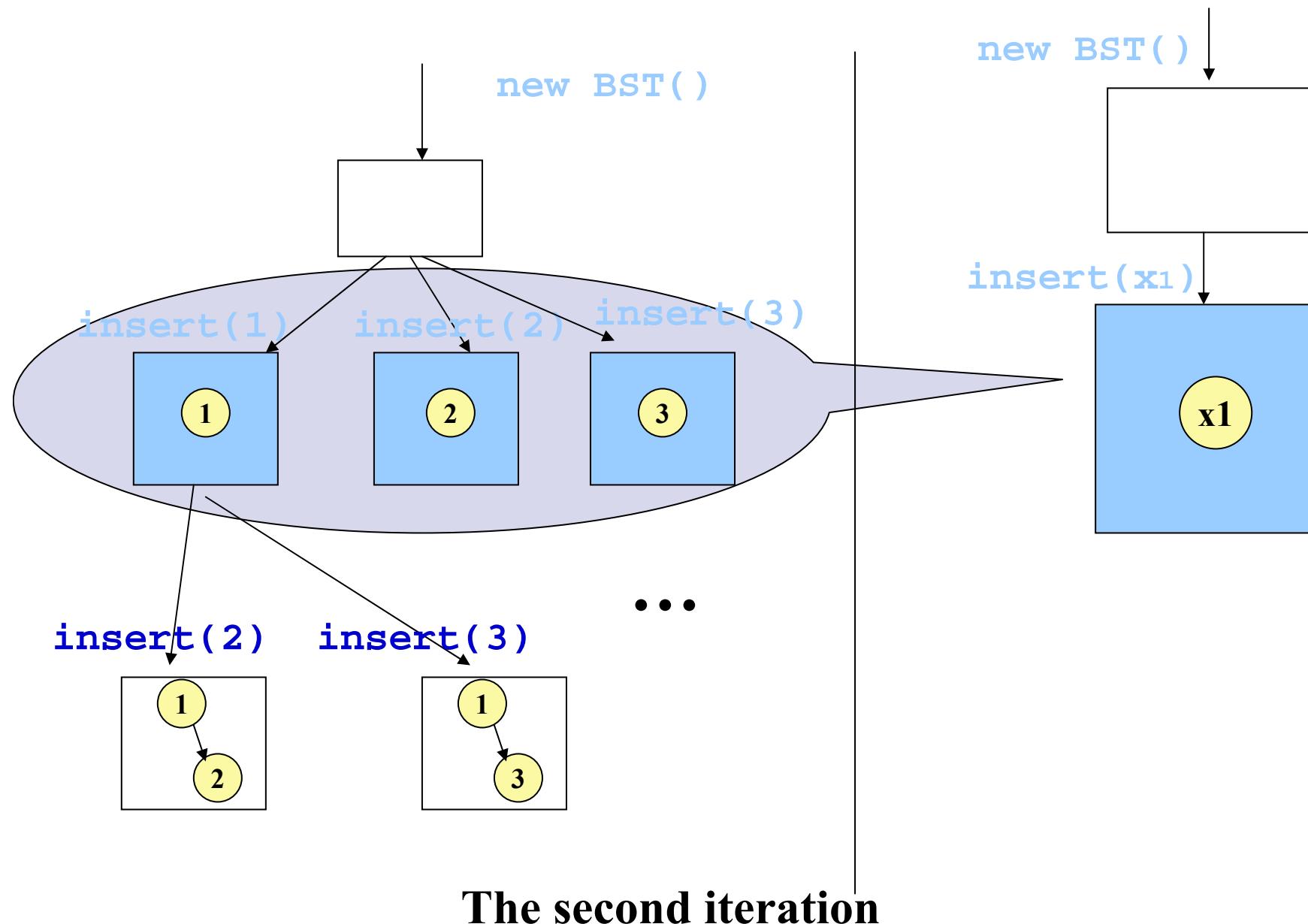
- State explosion (still)
  - need at least  $N$  different `insert` arguments to reach a BST with size  $N$
  - run out of memory when  $N$  reaches 7
- Relevant-argument determination
  - assume a set of given relevant arguments
    - e.g., `insert(1)`, `insert(2)`, `insert(3)`, etc.

# Exploring Concrete States

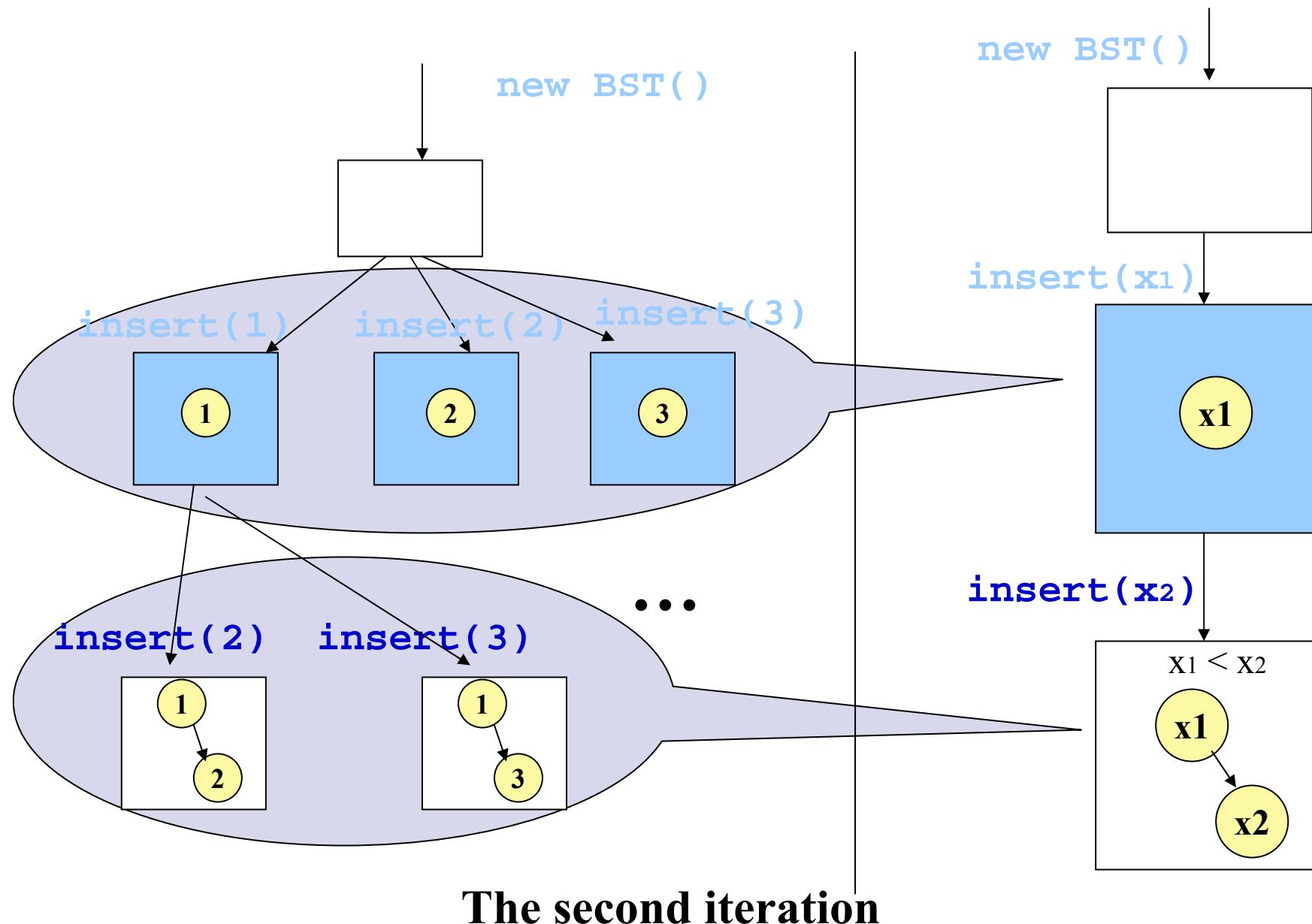


The second iteration

# State Abstraction: Symbolic States



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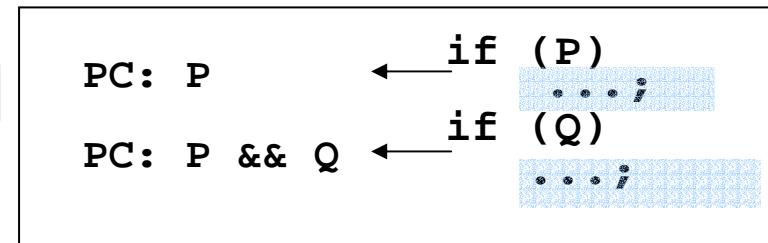


# Symbolic Execution

- Execute a method on symbolic input values

- inputs: `insert(SymbolicInt x)`

- Explore paths of the method

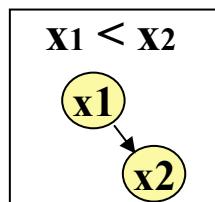


- Build a **path condition** for each path

- conjunct conditionals or their negations

- Produce **symbolic states** (<heap, path condition>)

- e.g.,

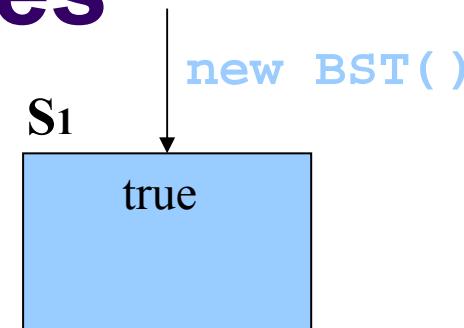


# Symbolic Execution Example

```
public void insert(SymbolicInt x) {  
    if (root == null) {  
        root = new Node(x);  
    } else {  
        Node t = root;  
        while (true) {  
            if (t.value < x) {  
                //explore the right subtree  
                ...  
            } else if (t.value > x) {  
                //explore the left subtree  
                ...  
            } else return;  
        }  
    }  
    size++;  
}
```

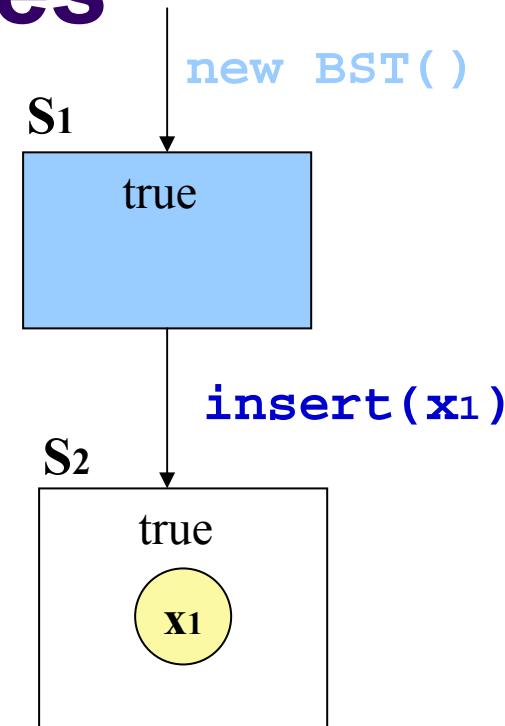
# Exploring Symbolic States

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            } else if (t.value > x) {  
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                ...  
  
            } else return;  
        }  
    }  
    size++;  
}
```



# Exploring Symbolic States

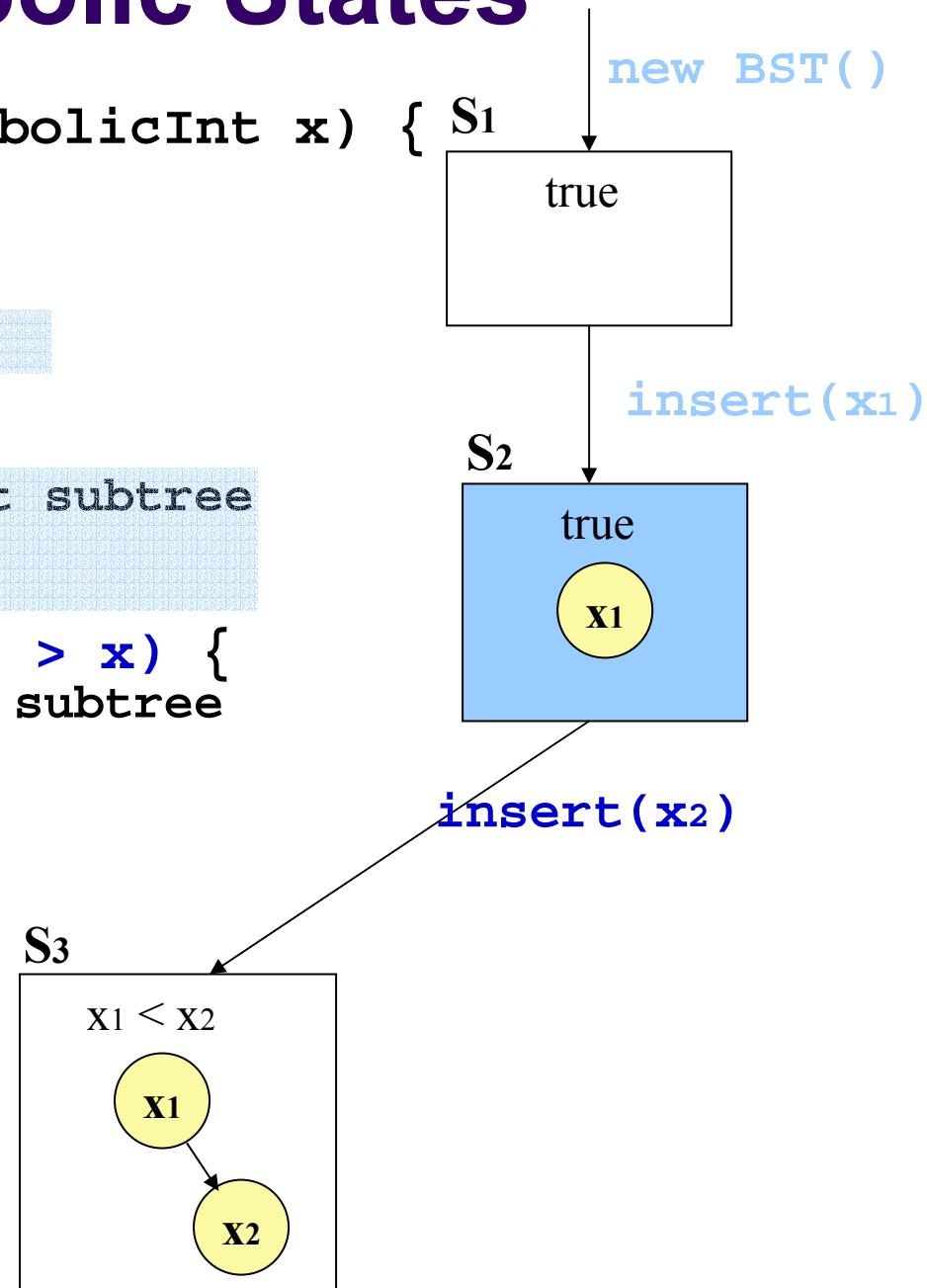
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                ...  
  
            } else return;  
        }  
    }  
    size++;  
}
```



The first iteration

# Exploring Symbolic States

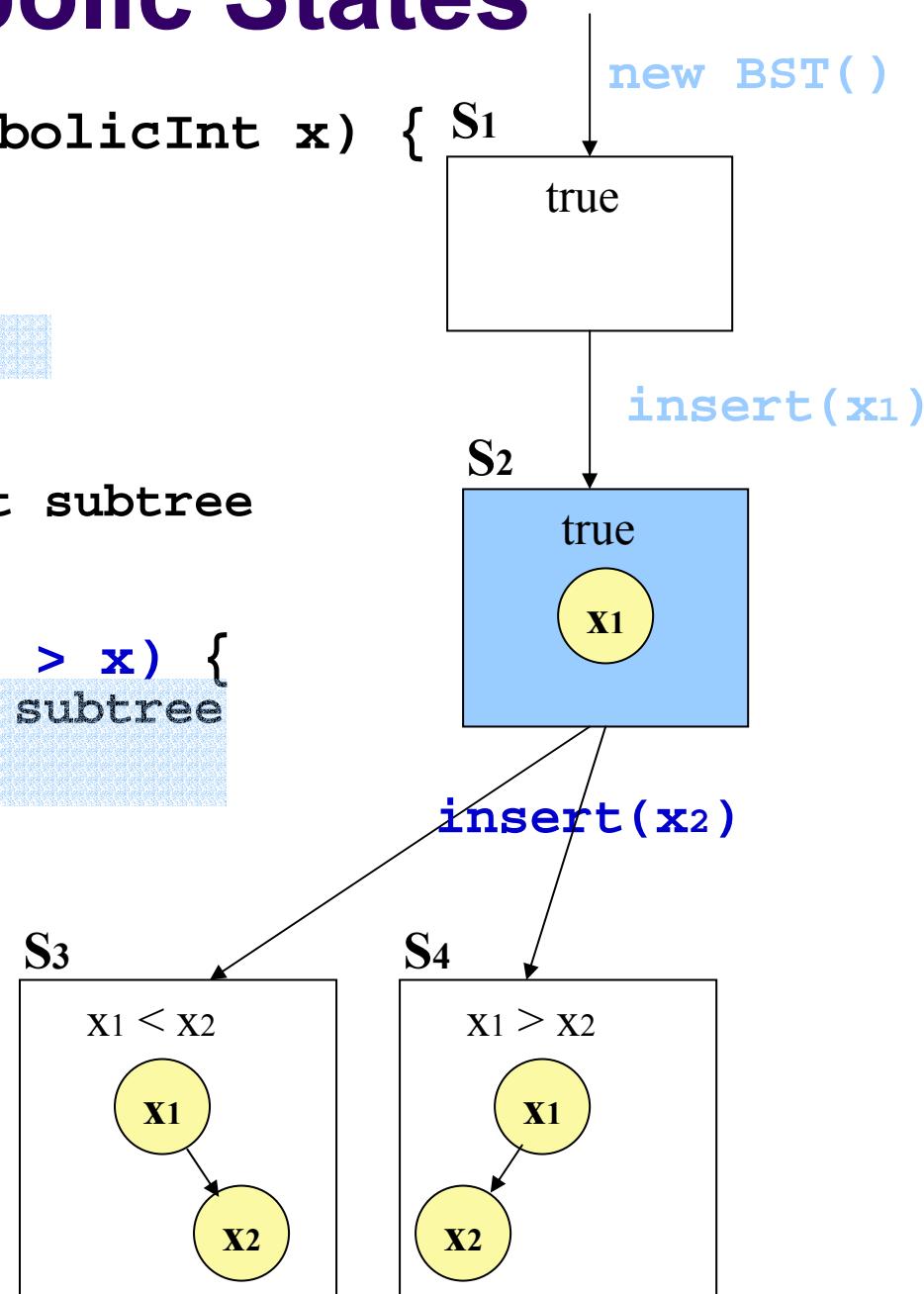
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                ...  
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                ...  
            } else return;  
        }  
    }  
    size++;  
}
```



# Exploring Symbolic States

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                ...  
  
            } else return;  
        }  
    }  
    size++;  
}
```

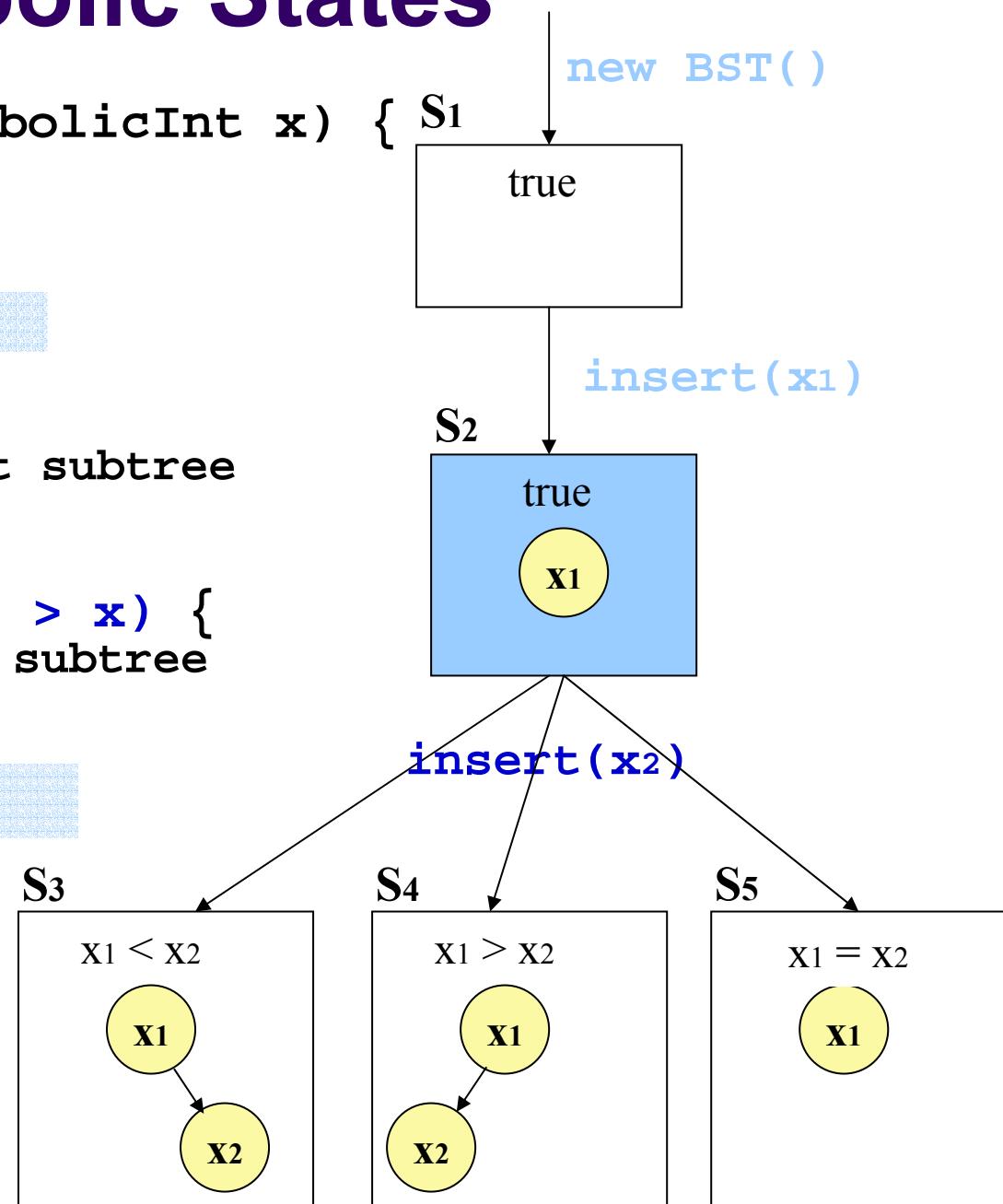
The second iteration



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            } else if (t.value > x) {  
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                ...  
  
            } else return;  
        }  
    }  
    size++;  
}
```

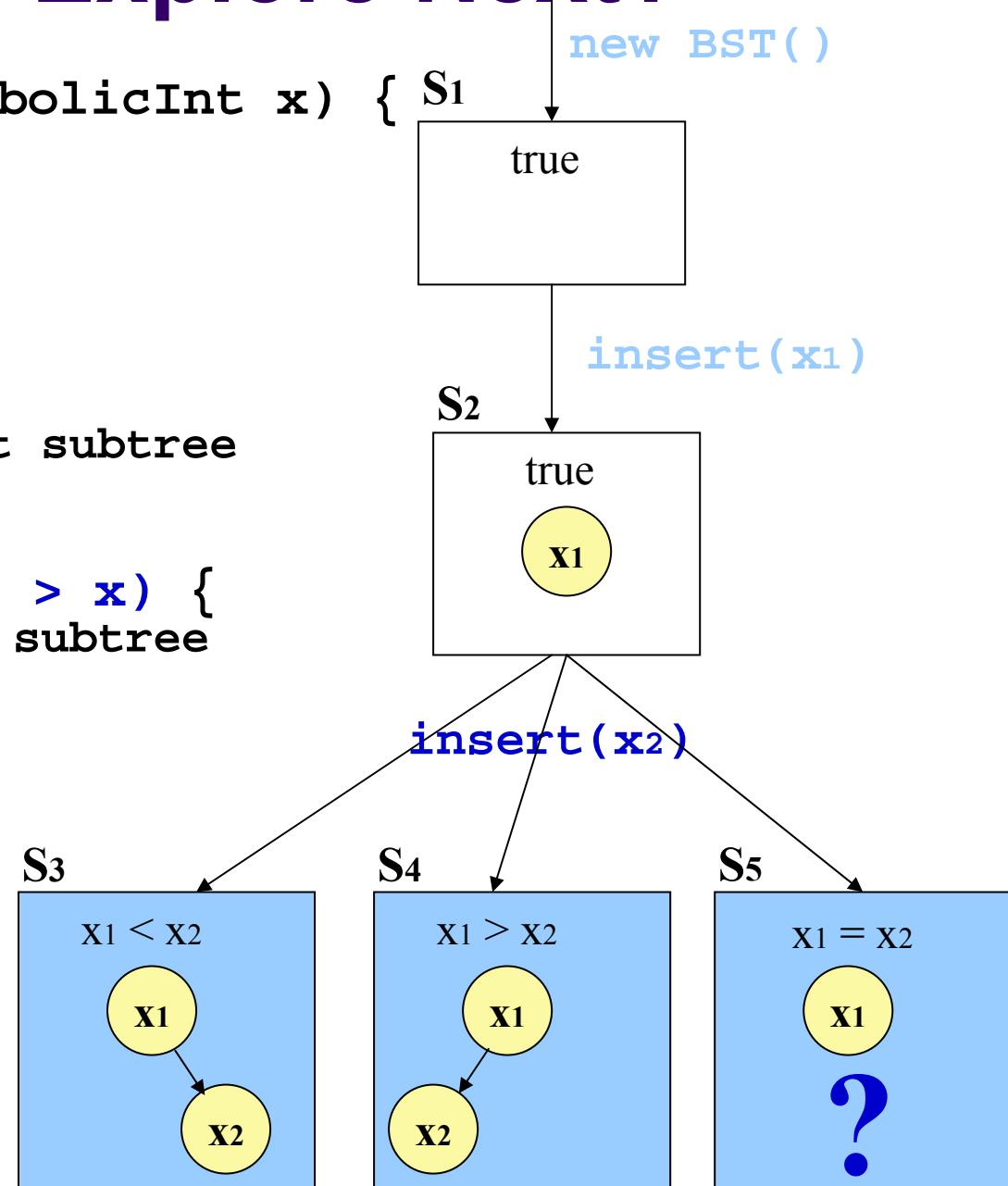
The second iteration



# Which States to Explore Next?

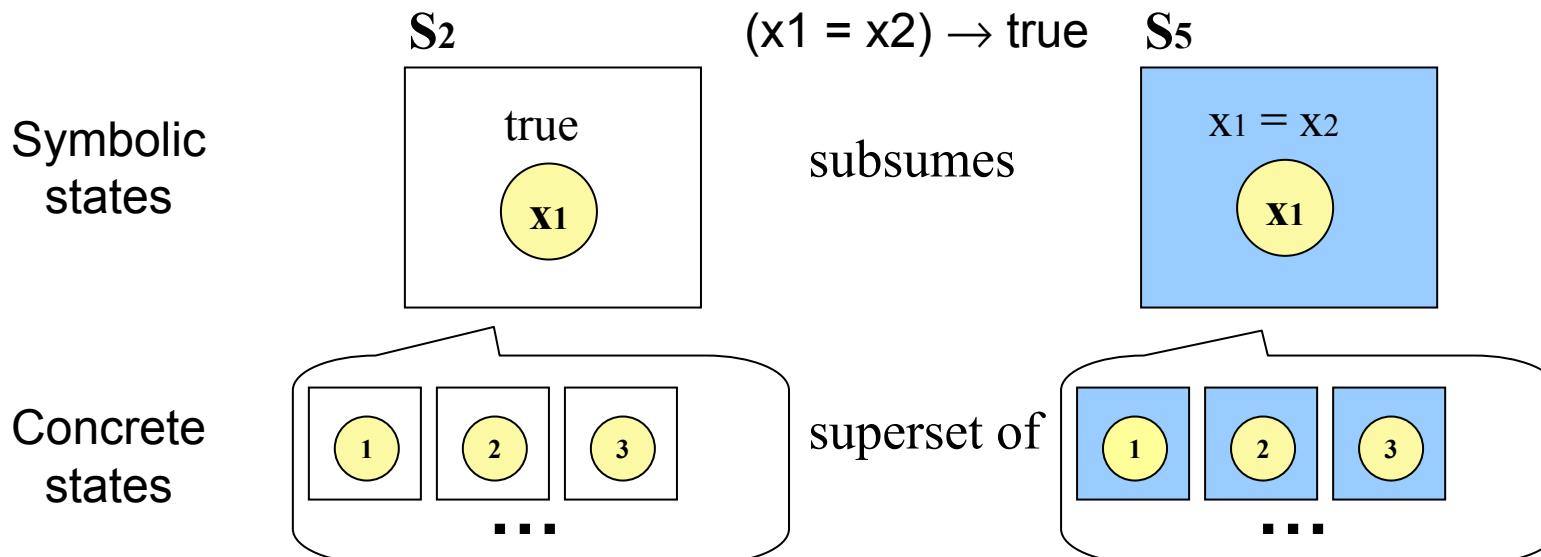
```
public void insert(SymbolicInt x) {  
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        root = new Node(x);  
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        Node t = root;  
        while (true) {  
            if (t.value < x) {  
                //explore the right subtree  
                ...  
  
            } else if (t.value > x) {  
                //explore the left subtree  
                ...  
  
            } else return;  
        }  
    }  
    size++;  
}
```

The third iteration



# Symbolic State Subsumption

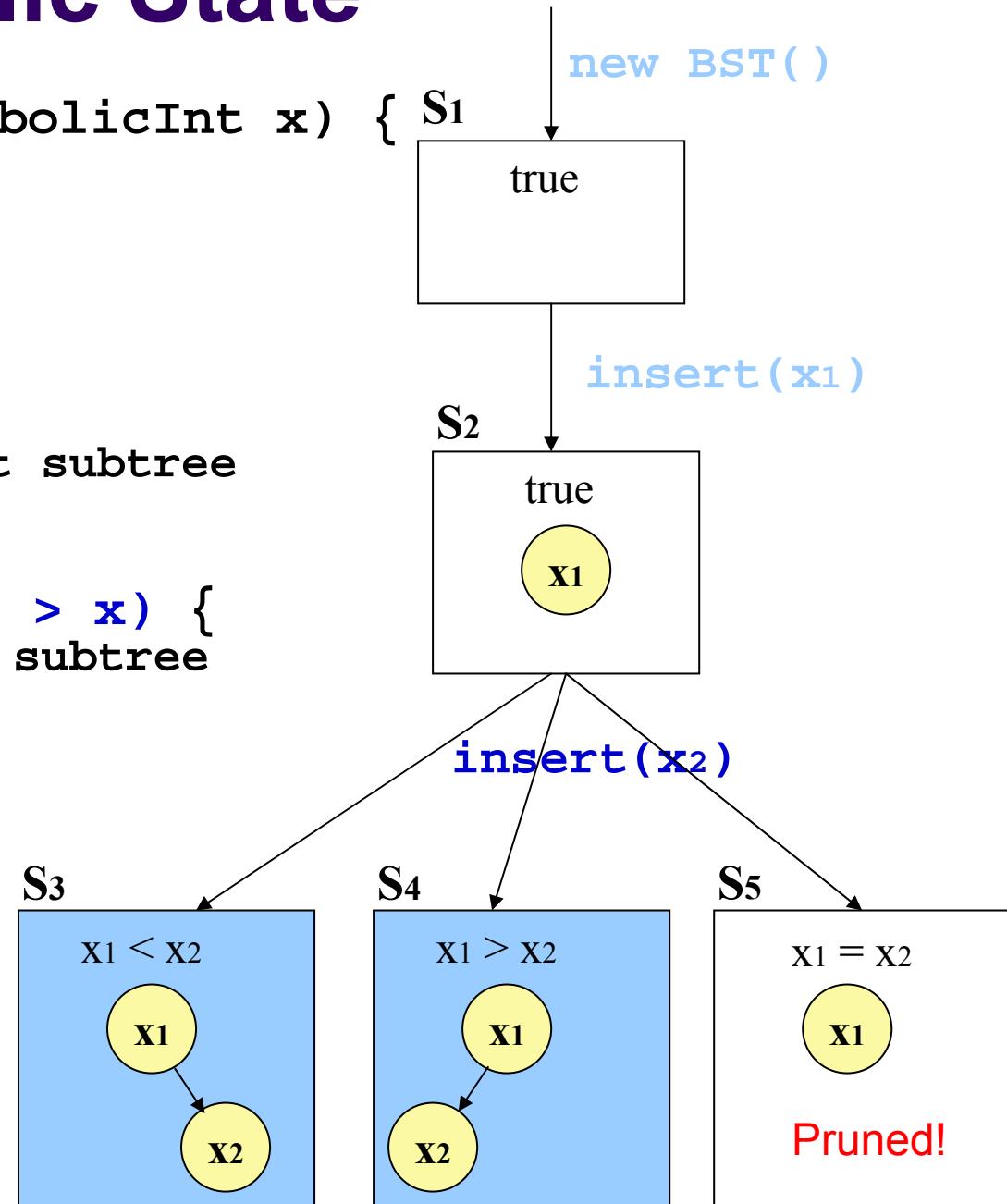
- Symbolic state  $S_2: \langle H_2, C_2 \rangle$  subsumes  $S_5: \langle H_5, C_5 \rangle$ 
  - Heaps  $H_2$  and  $H_5$  are isomorphic
  - Path condition  $C_5 \rightarrow C_2$  [CVC Lite, Omega]
- Concrete states represented by  $S_2$  are a superset of concrete states represented by  $S_5$
- If  $S_2$  has been explored,  $S_5$  is pruned.
  - Still guarantee path coverage within a method



# Pruning Symbolic State

```
public void insert(SymbolicInt x) {  
    if (root == null) {  
        root = new Node(x);  
    } else {  
        Node t = root;  
        while (true) {  
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            } else return;  
        }  
    }  
    size++;  
}
```

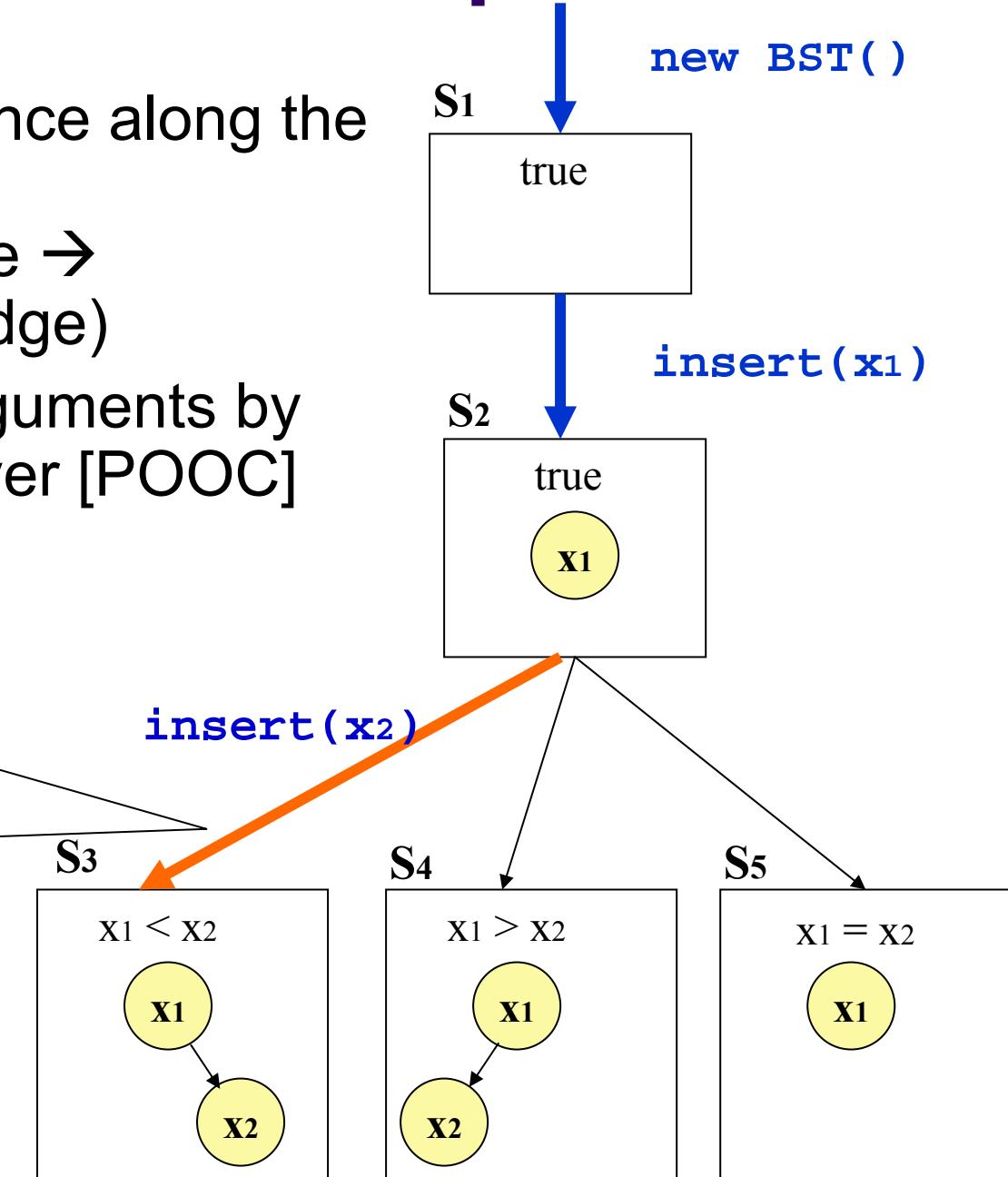
The third iteration



# Generating Tests from Exploration

- Collect method sequence along the shortest path  
(constructor-call edge → each method-call edge)
- Generate concrete arguments by using a constraint solver [POOC]

```
BST t = new BST();  
t.insert(x1);  
t.insert(x2);  
  
x1 < x2  
  
BST t = new BST();  
t.insert(-1000000);  
t.insert(-999999);
```



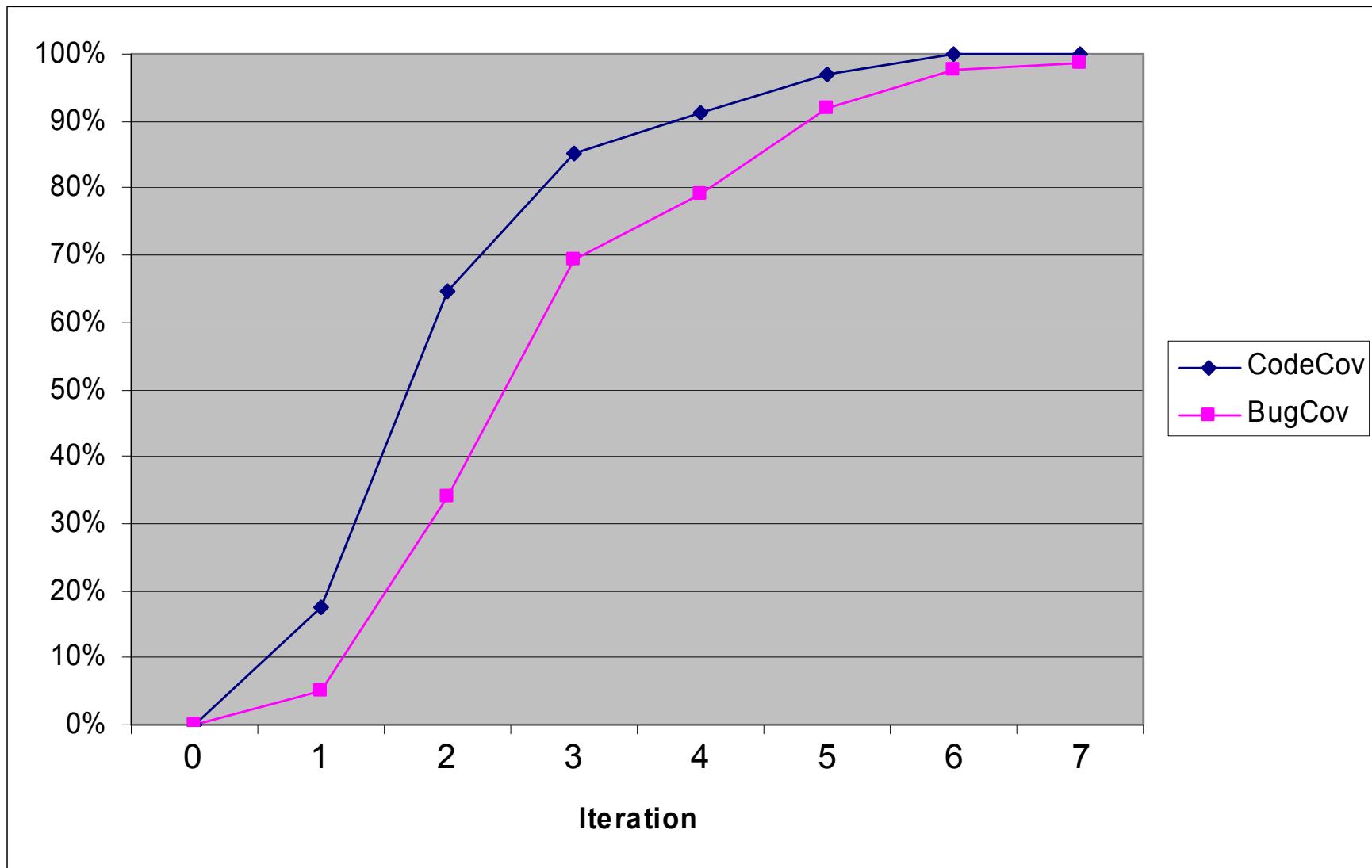
# Evaluation

- Generate tests up to  $N$  (1..8) iterations
  - Concrete-State vs. Symstra
- Focus on the key methods (e.g., add, remove) of seven Java classes from various sources
  - most are complex data structures
- Measure #states, time, and code coverage
- Pentium IV 2.8 GHz, Java 2 JVM with 512 MB
- Experimental results show Symstra effectively
  - reduces the state space for exploration
  - reduces the time for achieving code coverage

# Statistics of Some Programs

class	N	Concrete-State			Symstra		
		Time (sec)	#states	%cov	Time (sec)	#states	%cov
BinarySearchTree	6	23	731	100	29	197	100
	7	Out of Memory			137	626	100
	8	Out of Memory			318	1458	100
BinomialHeap	6	51	3036	84	3	7	84
	7	Out of Memory			4	8	90
	8	Out of Memory			9	9	91
LinkedList	6	412	9331	100	0.6	7	100
	7	Out of Memory			0.8	8	100
	8	Out of Memory			1	9	100
TreeMap	6	12	185	83	8	28	83
	7	42	537	84	19	59	84
	8	Out of Memory			63	111	84

# Code Coverage and (Seeded-)Bug Coverage with Iterations (Binary Search Tree)



# Related Work

Directly construct new valid object states

- Generating tests with concrete-state construction
  - e.g., TestEra [Marinov&Khurshid 01] and Korat [Boyapati et al. 02]
    - require specifications or **repOK** (class invariants)
- Generating tests with symbolic execution
  - e.g. NASA Java Pathfinder [Khurshid et al. 03, Visser et al. 04]
    - require **repOK** (class invariants)

# Conclusion

- Automated test-input generation needs to produce:
  - method sequences building relevant receiver object states
  - relevant method arguments
- Symstra exhaustively explores method sequences with symbolic arguments
  - prune exploration based on state subsumption
  - generate concrete arguments using a constraint solver
- The experimental results show Symstra's effectiveness over the existing concrete-state exploration approaches

# Questions?